

Scalar product of two vectors

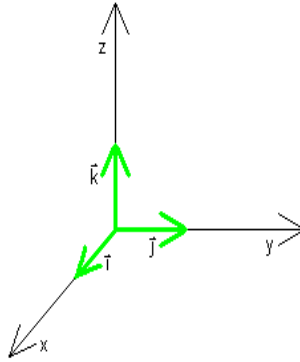
In the sequel we consider only the three dimensional Euclidian vector spaces, denoted by V_3 .

Based on the usual notations in \mathbb{R}^3 , a point P_0 can be written in Cartesian coordinate form as $P_0 = (x_0, y_0, z_0)$.

We will denote by $\overrightarrow{OP_0}$ the oriented line sequence, the position vector of the point P_0 , and for which we introduce the similar coordinates $\overrightarrow{OP_0} = \langle x_0, y_0, z_0 \rangle$.

We will have for two different points $P_1 = (x_1, y_1, z_1)$ and $P_2 = (x_2, y_2, z_2)$ in \mathbb{R}^3 , the oriented line sequence will be denoted by $\overrightarrow{P_1P_2}$, and we will use the coordinate form

$\overrightarrow{P_1P_2} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$, as obviously $\overrightarrow{P_1P_2} = \overrightarrow{OP_2} - \overrightarrow{OP_1}$. The class of congruence $\{ \overrightarrow{P_1P_2} = \langle a, b, c \rangle \mid P_1, P_2 \in \mathbb{R}^3 \}$ is by definition the vector $\vec{v} = \langle a, b, c \rangle \in V_3$. We mention 3 special vectors denoted $\vec{i} = \langle 1, 0, 0 \rangle$, $\vec{j} = \langle 0, 1, 0 \rangle$, $\vec{k} = \langle 0, 0, 1 \rangle$, the unit vectors of the 3 coordinate axis, named coordinate vectors.



Basic vector operations

We have $\vec{v} = \langle a, b, c \rangle = a\vec{i} + b\vec{j} + c\vec{k}$.

Scalar product of two vectors (dot product)

We define the external operation type $V_3 \times V_3 \rightarrow \mathbb{R}$ in the following way:

Given any two vectors $\vec{v}_1 = \langle a_1, b_1, c_1 \rangle$, $\vec{v}_2 = \langle a_2, b_2, c_2 \rangle \in V_3$, their scalar product, (named sometimes dot product) is: $\vec{v}_1 \cdot \vec{v}_2 = a_1a_2 + b_1b_2 + c_1c_2 \in \mathbb{R}$.

Properties

$\vec{v}_1 \cdot \vec{v}_2 = \vec{v}_2 \cdot \vec{v}_1$ commutativity

$\vec{v}_1 \cdot (\vec{v}_2 + \vec{v}_3) = \vec{v}_1 \cdot \vec{v}_2 + \vec{v}_1 \cdot \vec{v}_3$ linearity

$\vec{v} \cdot \vec{v} \geq 0$, the last one is used to introduce $|\vec{v}| = \sqrt{\vec{v} \cdot \vec{v}}$, named the length of the vector \vec{v} (norm).

The unit vector \vec{u}^0 of the vector \vec{u} is $\vec{u}^0 = \frac{\vec{u}}{|\vec{u}|}$, e.g. $\langle 3, 4, 12 \rangle^0 = \langle \frac{3}{13}, \frac{4}{13}, \frac{12}{13} \rangle$.

The scalar product of two vectors $\vec{v}_1 \cdot \vec{v}_2$ has an other interpretation:
 $\vec{v}_1 \cdot \vec{v}_2 = |\vec{v}_1| |\vec{v}_2| \cos \varphi$, where φ denotes the angle of the two vectors.

Applications

We deduce: $\cos \varphi = \frac{\vec{v}_1 \cdot \vec{v}_2}{|\vec{v}_1| |\vec{v}_2|}$, and we get an equivalent condition for the perpendicularity of two vectors, i.e. the nonzero vectors \vec{v}_1 and \vec{v}_2 are perpendicular iff $\vec{v}_1 \cdot \vec{v}_2 = 0$. (iff stands here for if and only if).

Vector projection

In order to define the projection of a vector \vec{v} onto vector \vec{u} we need first to get the length of the projection. If we check the figure below, we observe that $\vec{v} \cdot \vec{u}^0$

is exactly what we need, i.e. $\vec{v} \cdot \vec{u}^0 = |\vec{v}| \cos \varphi$.

The projection we look for is: $pr_{\vec{u}} \vec{v} = (\vec{v} \cdot \vec{u}^0) \vec{u}^0 = \frac{(\vec{v} \cdot \vec{u}) \vec{u}}{|\vec{u}|^2}$.

